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Blog: http://blog.chrisd.info
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GOAL:

• To become part of an intense software engineering team where I can make a big impact.

SKILLS:

- C, C++, C#, Java, Embedded Systems, Assembly, QT, MFC, Python, Perl, MySQL
- RTOS, Device Drivers, Hardware Interface, Multiprocessor, Distributed Systems
- Quick learner, Highly observant, Effective Multitasker with lots of energy

WORK EXPERIENCE:

TomTom, Expert Software Engineer/Tech Lead - Amsterdam, NL (2017-)

- Technical lead for the software platform team for the TomTom Bridge, which was responsible for many hardware upgrades of the TomTom Bridge, most notably the introduction of **4G** support, and the TomTom HUB. This included hardware and software requirements refinement, as well as hardware bringup support.
- Technical lead for the software platform teams in Amsterdam and Bangalore as we rolled out an **Android** upgrade from Jellybean to Marshmallow for all existing Bridge devices, and for the initial release of the TomTom HUB.
- Ported custom TomTom software from Jellybean to Marshmallow in C, C++, Java and Python.
- Developed and maintained the Android platform and automated tests for the Bridge and HUB line of products, and interfaced with customers to resolve customer issues when necessary.

TomTom, Senior Software Engineer - Amsterdam, NL (2014-2017)

- Worked on the whole Android stack for a wide range of TomTom navigation devices including the TomTom GO, Rider, Trucker, Bridge, and others. This work involved Linux device driver development, C++ HAL development, and Java development in the higher layers of Android.
- Assisted in the hardware bringup for the most recent TomTom GO in Taipei.

Amsterdam Scientific Instruments, Lead Software Architect - Amsterdam, NL (2012-2014)

- Worked closely with hardware development and physicists to build a new high speed readout system for Timepix CMOS X-ray sensors.
- Responsible for high level hardware architecture design, and full C/C++ software stack for the high speed readout system; including the following software modules:

- Linux device driver to interface directly to the FPGA, and DMA subsystems on x86 and Arm processors.
- Linux x86 and Arm firmware to interface with the device driver and store frame data on local hard drives, or send the frames over TCP/IP to a remote host.
- Developed a remote host API for Windows, Linux, and OSX to easily interface with the firmware from networked PCs using boost, and cmake to reduce cross platform differences.
- Developed a GUI plugin layer to interface the high speed readout system to Java based GUIs using JNI.
- Developed a fully automated unit test suite in python to test all major parts of the high speed readout system.
- Designed and developed the hardware and software for X-ray beam hardening calibration device.
 - PCB design of BeagleBone Black cape to drive 10 small DC motors, with 20 end stop switches.
 - Designed Linux firmware in C++ to run on the BeagleBone Black and provide an easy to use TCP/IP interface for networked PCs to control the beam hardening calibrator.
 - Developed a remote host C++ API for Windows, Linux, and OSX with Boost and cmake to allow easy command and control of the beam hardening calibrator.
 - Developed GUI module in **Java** with **JNI** to give end users full control of the beam hardening calibrator through the remote host API.
- Designed and developed the hardware and software for CMOS sensor temperature stabilization device.
 - PCB design of a small system that interfaces with Arduino Micro and controls Peltier modules to stabilize the temperature of the CMOS sensors.
 - Designed software for the Arduino to read the CMOS sensor temperature over I²C and implemented a PID controller to pulse width modulate the peltier based on the sensor temperature.
- Provided support and maintenance for previous generation of X-ray CMOS sensor readout systems.

Pegamento, Senior Software Engineer - Amsterdam, NL (2012-2012)

- Member of a team that develops Windows software to interface with legacy, web, and database systems in C#, C++, and javascript to modernize and automate business processes.
- Responsible for the system analysis to get an understanding of customer needs prior to solution development.
- Designing and developing a highly customisable web based CRM solution for small to medium businesses, that will be able to connect to legacy systems, web services, and databases.

Tekelec, Real Time Application Engineer - Amsterdam, NL (2010-2012)

- Member of an agile team that develops **Linux** and **Solaris** applications to facilitate mobile messaging (SMS), and related services.
- Develop next generation of subscriber database to manage 100 million subscribers in **MySQL Cluster**.
- Enhance **perl scripts** used for automated regression test in order to improve robustness and code coverage.

Tekelec, Embedded Real Time OS Software Engineer - Raleigh, NC (2002-2010)

- Member of a 10-person team that is responsible for developing a number of real time operating systems for a variety of embedded systems in C, x86 and ARM assembly; including:
 - Tekelec proprietary RTOS running on systems from the Intel 286 to the P4 Xeon, and Arm based IXP1250, IXP2350, and EP9312.
 - o VxWorks RTOS running on systems from the Intel 386 to the P4 Xeon.
- Implemented a number of low level modules; including: exception handlers/NMI, ISRs, SMBus interface, bootloader code, in system programming for devices such as FPGAs, flash chips, and CPLDs, and device drivers for 24 port Ethernet switch.
- Designed a number of high-level modules; including: application error reporting interface, live system fail-safe software upgrade, thermal management module (patent pending), Inter-processor communication module, **Multiprocessor** File I/O device driver.
- Developed a core infrastructure test application; this test application consisted of a server running on embedded VxWorks systems, and a MFC GUI client which communicates to the server over Ethernet.
- Collaborated with hardware team during board bring up for many new products.
- Troubleshoot, fix bugs, and develop enhancements in many different areas of the OS code base in both Rational ClearCase, and PVCS environments.

BOPS Inc., Embedded Applications Engineer - Raleigh, NC (2000-2002)

- Part of a team that designed, developed, tested, documented, and maintained a multi-platform real time embedded **DSP** OS. My responsibilities included **RTOS** design, host API design/development, compiler development, and system verification.
- Developed 2D/3D applications on the BOPS DSP iVLIW core in assembly, such as OpenGL 3D lighting model, and a 3D rasterization engine with perspective correct texture mapping.
- Actively participated in many other projects throughout the company including: coding standards committee, documentation standards committee, swat team, and the prototype team.

BOPS Inc., Toolset Developer - Raleigh, NC (internship, 1998-2000)

- Developed and maintained the BOPS DSP simulator, MFC debugger, GNU assembler, and other GNU utilities targeted for the BOPS platform.
- Implemented directed test case generators in Tcl, to verify the BOPS DSP simulator, and RTL.

EDUCATION:

North Carolina State University, Raleigh, NC (1996-2000)

- Bachelor of Science in Computer Science
- Concentration in 3D/Stereo Graphics programming

ACCOMPLISHMENTS:

- US Patent pending: Methods, systems and computer program products for thermal management of a processor associated with a network interface
- Publication: MacAllister, David F; Desjardins, Christopher J. "Geometric image processing of stereo pairs." Proc. SPIE Vol. 4297, p. 317-327 Abstract available at www.spie.org.

REFERENCES:

References available at http://nl.linkedin.com/in/chrisdesjardins/